

(12) NACH DEM VERTRAG ÜBER DIE INTERNATIONALE ZUSAMMENARBEIT AUF DEM GEBIET DES
PATENTWESENS (PCT) VERÖFFENTLICHTE INTERNATIONALE ANMELDUNG

(19) Weltorganisation für geistiges Eigentum
Internationales Büro



(43) Internationales Veröffentlichungsdatum
11. November 2004 (11.11.2004)

PCT

(10) Internationale Veröffentlichungsnummer

WO 2004/097546 A2

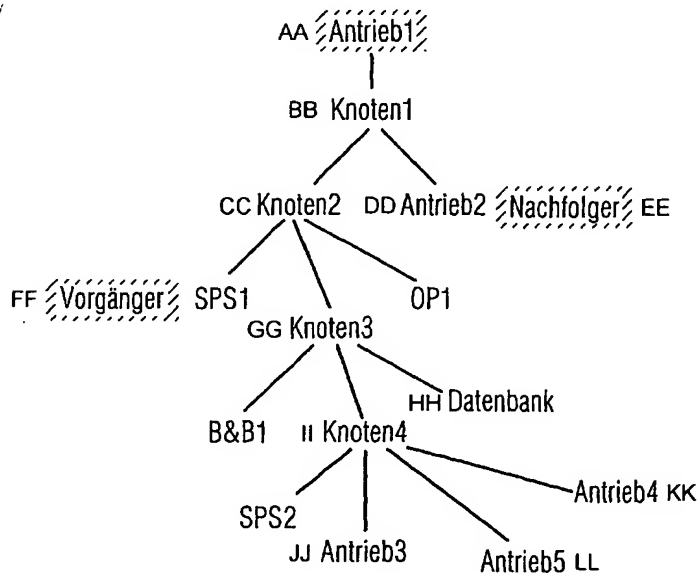
(51) Internationale Patentklassifikation⁷: G06F
(21) Internationales Aktenzeichen: PCT/EP2004/003071
(22) Internationales Anmeldedatum:
23. Februar 2004 (23.02.2004)
(25) Einreichungssprache: Deutsch
(26) Veröffentlichungssprache: Deutsch
(30) Angaben zur Priorität:
103 18 837.1 25. April 2003 (25.04.2003) DE
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(81) Bestimmungsstaaten (soweit nicht anders angegeben, für
jede verfügbare nationale Schutzrechtsart): AE, AG, AL,
AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH,
CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES,

[Fortsetzung auf der nächsten Seite]

(54) Title: METHOD AND DEVICE FOR IDENTIFYING AN ORDER IN A NETWORK

(54) Bezeichnung: VERFAHREN UND VORRICHTUNG ZUR ERKENNUNG EINER ORDNUNG IN EINEM NETZWERK



AA... DRIVE1
BB... NODE1
CC... NODE2
DD... DRIVE2
EE... SUCCESSOR
FF... PREDECESSOR

GG... NODE3
HH... DATABASE
II... NODE4
JJ... DRIVE3
KK... DRIVE4
LL... DRIVE5

(57) Abstract: The invention relates to a method for identifying an order of users (T1,T2,Td,...) of a network, whereby the network contains a multitude of nodes (S1,S2,Sn,...) and each of the nodes (S) has a number (MS) of connections (P1S,P2S,PaS,...,PMS) by means of which the nodes (S1,S2,Sn,...) and the users (T1,T2,Sd,...) can be interconnected. The inventive method comprises the following steps: a) identifying the node (Sn) connected to one of the users (Td); b) determining the number (MSn) of connections of this node (Sn) and a predetermined hierarchy of the connections; c) determining, for these nodes (Sn), the connection (PaSn) with which the user (Td) is connected to this node (Sn), and; d) determining, for the nodes (Sn), other connections (PavSn,PanSn) that are connected to other nodes (S1,S2,...) or to other users (T1,T2,...); e) establishing a relationship between users (T1,T2,Td,...) of the network based on the hierarchy of the connections that is predefined for node (Sn) and on the determined connections that are connected to users (T1,T2,Td,...) or to other nodes (S1,S2,...).

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FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.

EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Veröffentlicht:

— ohne internationalen Recherchenbericht und erneut zu veröffentlichen nach Erhalt des Berichts

(84) **Bestimmungsstaaten** (soweit nicht anders angegeben, für jede verfügbare regionale Schutzrechtsart): ARIPO (BW, GH, GM, KE, LS, MW, MZ, SD, SL, SZ, TZ, UG, ZM, ZW), eurasisches (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), europäisches (AT, BE, BG, CH, CY, CZ, DE, DK,

Zur Erklärung der Zweibuchstaben-Codes und der anderen Abkürzungen wird auf die Erklärungen ("Guidance Notes on Codes and Abbreviations") am Anfang jeder regulären Ausgabe der PCT-Gazette verwiesen.

(57) **Zusammenfassung:** Die vorliegende Erfindung betrifft ein Verfahren zur Erkennung einer Ordnung von Teilnehmern (T1, T2, Td,...) eines Netzwerkes, wobei das Netzwerk eine Vielzahl von Knoten (S1, S2, Sn,...) beinhaltet und jeder der Knoten (S) eine Anzahl (MS) von Anschlüssen (P1S, P2S, PaS, ..., PMS) aufweist, mittels derer die Knoten (S1, S2, Sn,...) und die Teilnehmer (T1, T2, Sd, ...) untereinander verbindbar sind, mit den Schritten: a) Erkennen des mit einem der Teilnehmer (Td) verbundenen Knotens (Sn), b) Feststellen der Anzahl (MSn) der Anschlüsse dieses Knotens (Sn) und einer vordefinierten Hierarchie der Anschlüsse, c) Ermitteln für diesen Knoten (Sn) den Anschluss (PaSn) mit dem der Teilnehmer (Td) mit diesem Knoten (Sn) verbunden ist, d) Ermitteln für den Knoten (Sn), weitere Anschlüsse (PavSn, PanSn), die mit weiteren Knoten (S1, S2,...) oder Teilnehmern (T1, T2,...) verbunden sind, e) Festlegen einer Beziehung zwischen Teilnehmern (T1, T2, Td, ...) des Netzwerkes anhand der für den Knoten (Sn) vordefinierten Hierarchie der Anschlüsse, und der ermittelten Anschlüsse die mit Teilnehmern (T1, T2, Td,...) oder weiteren Knoten (S1, S2,...) verbunden sind.

Description

Method and apparatus for identifying an order in a network

- 5 The present invention relates to a method and an apparatus for identifying an order in a network. The present invention particularly relates to a method and an apparatus for identifying an order of devices in a network. The present invention further relates to a computer program product for
10 implementing the method.

- Networks are known in many variants and embodiments for the most diverse applications. They are always used in situations where a large number of devices are to interact with one
15 another in complex arrangements.

- It is nowadays commonplace, for example, for a plurality of devices, e.g. computers and peripherals such as printers, to be interconnected using a so-called ethernet. For this purpose,
20 so-called nodes are provided at a large number of locations, such as inside a building. These nodes themselves in turn have a number of connections. The nodes are interconnected in such a way as to provide a basic framework for a network. One or more devices can now be linked into the network by means of the free
25 connections of the nodes. Data or even commands which are generated by a device such as a computer can then either be transmitted via the network to another computer connected to the network, or else they can be output to a printer connected to the network.
30

Another well-known example is the pooling of one or more controls, databases, operator units, drives, actuators and sensors to form a network within an automation system. Thus,

for example, commands can be entered centrally via an operator unit which are first forwarded via the network to a control and then to the corresponding actuators or other units.

5 It is essential for all these implementations and applications that information as to which devices are actually in the network is available within the network. US 5,574,860, for example, discloses a network which determines by means of a
10 central unit which devices are currently present in the network. For this purpose the central unit sends a large number of requests via the network. As soon as a device is connected to the network, it sends a message acknowledging the request to the central unit. On the basis of the acknowledgment messages, the central unit determines which devices are currently
15 connected to the network.

In addition, WO02/05107 describes an industrial network whereby, in the event of device failure, a central unit ensures reconfiguration as soon as maintenance personnel have replaced
20 the defective device.

The disadvantage of the method described in US 5,574,860, however, is that a number of requests proportional to the number of nodes in the network is necessary in order to
25 ascertain which devices are connected to the network. This method is therefore very complex and time consuming. Particularly when a comparatively large number of devices are connected to the network, much time is required for identifying and ordering the devices. The method described in WO02/05107
30 has the disadvantage that a reconfiguration is always centrally controlled by a unit.

The object of the present invention is therefore to specify a method and an apparatus providing a simple way of identifying an order in a network.

- 5** This object is achieved by the method according to claim 1, wherein the network contains a large number of nodes and each of the nodes has a number of connections by means of which the nodes and the devices can be interconnected, comprising the following steps:
- 10** a) identifying the node connected to one of the devices,
b) ascertaining the number of connections of this node and a predefined hierarchy of connections,
c) determining for this node the connection with which the device is connected to this node,
- 15** d) determining for this node other connections which are connected to other nodes or devices,
e) establishing a relationship between devices in the network, on the basis of the connection hierarchy predefined for this node and of the determined connections that are connected to
- 20** devices or other nodes.

The object is further achieved by the apparatus according to claim 13, having

- means of identifying the node connected to one of the
- 25** devices,
- means of determining the node connection with which the device is connected to the node,
- means of determining other connections of the node which are connected to other nodes or devices,
- 30** - means of establishing a relationship between network devices, on the basis of the connection hierarchy predefined for the node and of the determined connections that are connected to devices or other nodes.

By the very fact that the connection hierarchy for each node is defined or known in advance, a hierarchy of occupied connections can be deduced for each of the nodes as soon as the
5 occupied connections have been determined. The term occupied connections will hereinafter be used to designate connections of a node which are connected to other nodes or devices of the network. This means that it is possible, using only a small
10 number of steps and therefore very rapidly, to ascertain for each device in the network a relationship to other devices in the network. As the hierarchy of occupied connections is known for each node, a relationship between devices across a plurality of connected nodes can also be determined in a simple manner. Means of assuming these tasks and ascertaining the
15 relationship between devices in a network within a very short time can be provided accordingly.

If the individual procedural steps are executed on a decentralized basis, i.e. by each device in the network, an
20 order of the devices in a network can be very quickly identified taking very little time. Particularly in the event of device failure, for example, there is no need for the entire network to be reconfigured by a central unit once the device has been replaced. Instead, reconfiguration can take place on a
25 decentralized basis in the vicinity of the replaced device.

In particular, each device's upstream neighbors and downstream neighbors can be established from the established order of devices. This is advantageous, for example, if the devices in
30 the network belong to groups having different functions. The nearest device from a group having a specific function can thus be ascertained very quickly for each device.

If the procedural steps are repeated in whole or in part at periodic intervals, each device can detect on a decentralized basis, i.e. for itself, changes in its environment and respond accordingly. As soon as a change is ascertained, this change
5 can be responded to on a decentralized basis and not by the entire network via a central unit. This is particularly advantageous when nodes or even devices are dropped or newly added or failed devices have to be replaced. There is then no
10 need for the whole network to respond to the change via the central unit. Instead the network can be reconstructed on a decentralized basis using the established and therefore known order of the devices, i.e. using the upstream neighbors and downstream neighbors.

15 Particularly if the relationship of the devices to one another established according to the present invention is stored in appropriate means in devices or nodes, reconstruction can take place very quickly locally if a device replacing another requests the stored relationship of the old device from its
20 neighbor, i.e. upstream neighbor or downstream neighbor. These means can be any kind of storage such as hard disks, diskettes or even memory devices such as flashes.

A computer program product for performing the procedural steps
25 according to the present invention allows new devices to be rapidly linked into the network.

The principle of the present invention will now be explained in greater detail in the following description with reference to
30 the Figures in which:

Fig.1 shows a first implementation in an automation system,

Fig. 2 schematically illustrates an order of the first implementation, and

Fig. 3 shows a second implementation for a rail vehicle.

5 Fig. 1 shows a first implementation of the present invention of the kind that can be provided in an automation system. A large number of nodes S_n , S_2 , S_3 and S_4 are interconnected, each of the nodes having a number of connections. For example, the node S_3 has the connections $P1S_3$, $P2S_3$, $P3S_3$ and $P4S_3$. The node S_3 is connected by means of its connection $P1S_3$ to the connection $P3S_2$ of the node S_2 . The latter is in turn connected by means of the connection $P1S_2$ to the connection $P1S_n$ of the node S_n . The other connections which are not occupied by nodes can be occupied by other devices such as controls, databases, operator units, drives, sensors or actuators. For example, the node S_3 is connected via the connection $P2S_2$ to an operator unit $B\&B1$ and via the connection $P2S_3$ to a database 1. In addition, the node S_n is connected via the connection PaS_n to a drive 1 as device T_d and via connection $P3S_n$ to a drive 2 as device T_2 . In addition to the above-mentioned assignment, the node S_2 is additionally connected via $P2S_2$ to a stored program control $SPS1$ as device T_3 and to an operator unit $OP1$ as device T_4 .

25 The principle of the present invention will now be described in greater detail using as an example the drive 1 which is designated as device T_d in the network. It is first necessary to identify the node to which the device T_d is connected. This can be done, for example, by means of a discovery protocol which at the same time also allows the connection PaS_n of the associated node to be determined. As soon as the node S_n has been identified as the node associated with the device T_d , it must be ascertained in a next step how many connections the node possesses in total. In this example the node S_n has three

connections, namely P1Sn, PaSn and P3Sn. In addition, the generally predefined hierarchy of the connections of node Sn must be ascertained. In the present case the following hierarchy is assumed: P1Sn<PaSn<P3Sn. In another step it must

5 be ascertained which of the connections P1Sn, PaSn and P3Sn of the node Sn are still occupied. This takes place, for example, by means of an interrogation as to which MAC (Media Access Control) addresses are available at which of the connections. For this purpose an interrogation can take place by means of a

10 protocol such as an Internet Protocol (IP) as to which IP address is assigned to which MAC address. In the present example it will therefore be ascertained that a drive 1 is connected to connection PaSn as device Td and a drive 2 is connected to connection P3Sn directly as device T2. The steps

15 just described of the method according to the invention in respect of the node Sn must be performed correspondingly in respect of the other nodes of the network. For example, the node S2 has the four connections P1S2, P2S2, P3S2 and P4S2 to which other devices of the network are connected. The stored

20 program control SPS1 is connected via connection P2S2 as device T3, and the operator unit is connected via connection P4S2 as device T4. Furthermore it will be assumed that the connections of the node S2 have the hierarchy P1S2<P2S2<P3S2<P4S2. As the nodes S2 and Sn are directly interconnected, the devices T3 and

25 T4 are also indirectly connected to the node Sn via the node S2. Accordingly, the IP addresses of devices T3 and T4 can then in turn be ascertained using IP protocols. In a last step, the relationship between the devices must now be defined. From the relationship P1Sn<PaSn<P3Sn of the connections of the node Sn

30 it can be directly deduced that the device T2 is the downstream neighbor of device Td, as T2 is connected to P3Sn and Td is connected to PaSn. In the other direction, it can be ascertained via the same relationship that the node S1 is the

upstream neighbor of device Td, as S2 is connected to P1Sn and Td is connected to PaSn. As the relationship $P1S2 < P2S2 < P3S2 < P4S2$ in turn exists for the node S2 and the node Sn is connected to P1S2 and the device T3 is connected to P2S2,

5 the upstream neighbor of device Td can therefore be determined indirectly. As this can be continued accordingly for all the devices of the network, an order of all the devices in the network can therefore be demonstrated via the predefined and therefore known hierarchy of the connections of the individual

10 nodes and the knowledge of which connections are occupied. The resulting order for the implementation shown in Fig.1 is schematically illustrated in Fig. 2. It should be noted that the hierarchy of the connections of a node only specifies a direction but gives no direct indication as to which is an

15 upstream neighbor or a downstream neighbor. This definition is freely selectable as long as only the relationship of the connections of all the nodes present in the network have the same orientation.

20 The present invention can then be advantageously used, for example, when it comes to replacing a defective drive in an automation network. Assuming that drive 1 is defective and is replaced by a maintenance engineer, the new drive must first identify which node it is assigned to and which devices are its

25 neighbors, e.g. upstream neighbor or downstream neighbor. If the device T3 has a flash memory in which the relationship or order of Td with respect to T3 determined according to the present invention is stored, the device T3 can provide the replacement device Td with the corresponding stored data as

30 soon as the device Td has identified the device TS as a neighbor. The replacement device Td can then take over the functions of the old drive directly and without major loss of time. As this takes place locally in a limited vicinity within

the network, no time-consuming replanning or reconstruction of the network by a central unit is required.

- The embodiment just described in relation to an automation system can of course also be used in similar or modified form in other networks such as an ethernet containing computers and peripherals as devices. The essential feature is always the local and therefore rapid identification of orders of devices. For example, it may be advantageous for a computer to know whether its immediate neighbor is another computer or even a printer. On the other hand it is necessary to determine in which direction the nearest device available in the network is located. For example, it may be important for a computer to know in which direction the nearest printer available in the network is located. It should be noted here, and also in the description in relation to the other implementations, that the terms "direction" and "vicinity" do not necessarily refer to a spatial assignment of the devices of a network. Rather these terms are intended to describe the order of the network.
- Although identification of a spatial assignment is not part of the essential basic idea, it can play a role in the application of the present invention, as will now be shown with reference to a second implementation.
- Fig. 3 shows a second implementation of a kind that can be used, for example, in a means of rail transport. The network here is in a means of rail transport comprising a traction vehicle Z and the cars W1, W2, W3 and W4. The cars W1 and W4 are restaurant cars and therefore belong to a first group of devices. The cars W2 and W3 are passenger cars and belong to another group of devices. The traction vehicle Z contains the node S1. Each of the cars contains a corresponding node S2, Sn, S4, and S5. The node S2 in car W1 has 6 connections P1S2-P6S2

with the hierarchy $P1S2 < \dots < P6S2$. The node S_n in car $W2$ has 7 connections $P1S_n - P7S_n$ with the hierarchy

$P1S_n < \dots < PaS_n < \dots < P7S_n$. Car $W3$ contains the node $S4$ with the connections $P1S4 - P6S4$ and the hierarchy $P1S4 < \dots < P6S4$. The

5 node $S5$ in car $W4$ also has 6 connections $P1S5 - P6S5$ with the hierarchy $P1S5 < \dots < P6S5$. The individual nodes are interconnected in a sequence corresponding to the car

arrangement. To each of the node connections there is connected a computer in each case. For example, the computer of the car

10 $W2$ is connected to a connection PaS_n and shall hereinafter be referred to as device T_d . Correspondingly a device $T1$ is in the traction vehicle Z , a device $T2$ in $W1$, a device $T4$ in $W3$ and a device $T5$ in $W4$. On the basis of the disposition of the

connections and their hierarchy, the neighbors, for example, of

15 device T_d can now be determined using the present invention.

For this purpose, again the node S_n to which the device T_d is connected must first be determined. Accordingly the number of available connections of the node S_n as well as the hierarchy must be determined, then the connection PaS_n to which the

20 device T_d is connected must be determined, as well as the other connections which are connected to other nodes or connections.

The same must be done for the other nodes $S1$, $S2$, $S4$ and $S5$.

Finally the relationship of the devices $T1$, $T2$, T_d , $T4$ and $T5$ to one another then still has to be established. In this

25 implementation it emerges that the device $T4$ and then device $T5$ are in one direction, i.e. in the direction of the end of the

train. The $T2$ and then the $T1$ in the traction vehicle are in the other direction, towards the traction vehicle itself. Via the IP addresses of the individual devices, which then also

30 identify device $T2$ and device $T5$ as restaurant cars $W1$ and $W4$ and therefore as belonging to one group of devices, the

computer as device T_d in car $W2$ can provide the passengers with information as to the direction in which the nearest restaurant

car is situated, i.e. in this case in the direction of the traction vehicle. In this application also, the present invention allows dynamic and therefore rapid adaptation, in this case of the passenger guidance system, as soon as the
5 disposition of the cars changes, e.g. in the event of remarshalling.

Although the present invention has been described with reference to the two embodiments shown, it is not limited to
10 these two implementations. Rather the invention can always be used when it is question of locally establishing an order of devices within a network and therefore reacting quickly to local changes of devices in the network. The use of the method and apparatus according to the invention is also independent of
15 the structure of the network, whether it be a one-dimensional network as in the case of the means of rail transport, or even a multidimensional network as in the automation network described. For example, in many cases it may be important to ascertain the immediate neighbor of a device. In other
20 applications it is important to ascertain the nearest device in a particular group of devices. The present invention allows changes in the network to be responded to dynamically by means of the local availability of knowledge of an order of devices within the network.

25